## Mapping the Course Topics to the Student Outcomes' Aspects [Table (c)]

	6-1-	6	Carrier Taurier	Α		В				С			D				Ε			F		G			Н				I			J	1	K
	Code	Course	Course Topics	Α1	A2	В1	B2	B3	B4	C1	C	C3	D1	<b>D2</b>	D3	D4	E1	E2	E3	F1	F2	<b>G</b> 1	<b>G2</b>	<b>G3</b>	H1	H2	НЗ	H4	11	12	13	11	12	K1
			Basic DC circuits elements				<b>✓</b>	<b>√</b>	<b>✓</b>				<b>√</b>	<b>√</b>		\ \	-																	
			and its connection	L			•	Ť	ľ				•	•	Ľ	ľ																		
			Ohm's law and Kirchhoff	ĺ			✓	<b>✓</b>	/				<b>√</b>	<b>√</b>		/ /	-																	
			laws.	L					Ľ																									
m			Circuit analysis technique	L	$\checkmark$	✓	✓	✓					✓	✓	✓	<b>√</b>															ı			
Term	EE 231	Electrical Circuits I	Determination of the	ĺ																											ı			
<u> </u>			suitable load which provide	ĺ	✓		✓	✓	<b>✓</b>				✓	✓	` ✓	[ ✓															ı			✓
Ĕ			maximum power transfer	L																														
			RLC circuit and The	ĺ																											ı			
			relation between voltage and	✓																											ı			
			current	L																											ı			
		Assesment Method		Wr	itte	n Ex	am,	, As	sigr	ıme	nts	and	Lab	ora	tor	y Gr	oup	Wo	rk.															
			Revision on alternate	ĺ																														
			current series circuit and	ĺ			✓	✓	✓				✓	✓	` ✓	<b>1</b> ✓															ı			
			rest of other methods	L																														
			Complex power and	ĺ																											ı			
			maximum power	ĺ	✓																										ı			
	EE 232	Electrical Circuits II	calculations.	L																											ı			
			Three-phase balanced and	ĺ																											ı			
			unbalanced systems and its	ĺ	✓																										ı			
			power calculation	L																														
			Natural and step response in	ĺ	<b>✓</b>	✓	<b>✓</b>	<b>✓</b>	/				<b>√</b>	<b>√</b>		/ /															ı			
			RLC circuits	L																														
		Assesment Method		Wr	itte	n Ex	am,	, As	sigr	ıme	nts	and	Lab	ora	tor	y Gr	oup	Wo	rk.															
			Accuracy of measurement	✓			✓	✓	✓																									
			and error analysis	ĺ																											ı			
4			and onto analy 515	L						_	1				_	1	1			L		<u> </u>		_		_		Ш					_	_
]			Absolute & secondary	i																1														J

ے ا	1		Ausolute & secondary																						I		Ī		
Term			Moving coil	✓	<b>√</b>		✓	✓	<b>✓</b>																				
			Dynamometer	✓	<b>√</b>																								
	EE 211	Elect Meas & Inst. I	Induction instruments	✓	✓																								
			Measurement of active power and power factor		<b>√</b>																						Ì		
			DC and AC bridges		✓		✓	✓	✓																				
			Current and potential transformers		✓																								
			Oscilloscope.																					Ì					
		Assesment Method		Wr	itter	ı Ex	am,	Ass	ign	me	nts a	nd I	Labo	orate	ory	Wo	rk.												
			Signal conditioning circuit	✓	✓	✓	✓	✓	✓	✓		✓																	
			Transducers	✓	✓		✓	<b>√</b>	✓												✓	✓							
			Filters (active and passive)	✓	✓	✓	✓	✓	✓	✓		✓																	
	EE 312	Elect Meas & Inst. II	Convertes (ADC and DAC)	✓	✓																								
			Digital measurment (digital voltmeter and counter)		✓		✓	✓	<b>✓</b>																				
		Assesment Method		Wr	_	ı Ex	am,	Ass	ign	emi	nts a	nd I	Labo	orate	ory	Wo	rk.												
			Magnetic circuit principles		✓																			 _		_	$\downarrow$	$\perp$	Ш
2	EE 321	Electrical Machines I			✓														✓	✓									
٤			Types of DC motors and Generators		✓		✓	✓	✓																				

_ Le_		Assesment Method		Wr	ittei	n Ex	am	, As	sign	emi	nts a	and	Lab	orat	ory	/ Wc	rk.																
			Elements of Power System		✓															✓	<b>✓</b>								✓	✓	✓ .	✓	
			Power system Transmission	<b>√</b>	<b>✓</b>												<b>✓</b>	/	<b>✓</b>												Ι.	/	
			systems		Ĺ												Ľ	Ľ	Ľ										Ш				
			Economics of power system	✓	✓					✓	✓						✓	✓	✓							✓			Ш			✓	
EE 3	341	Intr. to Power	Parameters of O.H.T.L. &	<b>√</b>	<b>√</b>												<b>✓</b>	<b>✓</b>	<b>✓</b>														
			its's design															_		_									ightharpoonup		_		
			Corona Phenomena	✓	✓												✓	✓	✓	_					✓		✓	✓	$\dashv$		_		_
			Mechanical design of power	✓	✓					✓	✓						✓	✓	✓														
	H		system Tramsmission		Ш	Ļ		Ļ	Ļ		Ļ	L.	<u> </u>		Ļ					<u> </u>								Ш	Ш				
_		Assesment Method		Wr	itte	n Ex	am	, As	sign	emi	nts a	and	Res	eard	ch.		_	_		_	_	_	_	_				_	—	-	_	_	
			Complex frequency method	✓	✓													✓	✓														
			for different wave forms														-			-		<b>!</b>							$\dashv$	-		+	
			Laplace transform and	✓	✓												✓	✓	✓										1				
EE 3	332	<b>Network Analysis</b>	electric circuit sources Linear and Ideal																	╂		┢							$\dashv$		╂	-	-
			Transformers	✓	✓													✓	✓														
			Two port networks and it's														-			╂								$\Box$	$\dashv$		-		-
			different equation forms	✓	✓												✓	✓	✓										1				
		Assesment Method	different equation forms	Wr	itte	n Ex	am	and	l As	sign	mer	nts.																_	$\dashv$				
			Basics of Power Electronics		✓	✓	✓		✓	Ť			✓	✓	✓	✓	✓	✓	✓	T								T	П	T	Т	T	
			Thyristors & Their Firing	<b>✓</b>														_	<b>✓</b>	1											1		
		Danie Flantino i de l	angle	•	<b>√</b>												✓	✓	~														
EE 4	421	Powe Electronics I	Single/Three phase	<b>√</b>	<b>√</b>														./														./
			Converter	•	ľ														ľ										Ш				Ľ
			Power Factor Improvement	✓													✓	✓											Щ				
		Assesment Method		Wr		n Ex	am	, As	sign	emi	nts,	Lab	orat	ory	Wo	ork a	and	Min	i-Pro	ojec	t.												
			Per Unit System		<b>√</b>													_		_								Ш	ightharpoonup		_		
			Reactive Power Control	✓	✓												✓	✓	✓	┡						✓			$\dashv$		_		<b>✓</b>
			Power Flow Analysis using	✓	✓												✓	✓	✓														✓
EE 3	342	Power System I	Gauss-Siedel																	-		<b>.</b>							$\dashv$			-	-
			Power Flow Analysis using	✓	✓												✓	✓	✓										1				✓
			Netwon Raphson	✓	<b>✓</b>												./	<b>√</b>	./	╂	-					./	./		$\dashv$			./	-/
		Assesment Method	Economic Dispatch		itte	n Ev	am	and	٨٥	cian	mer	ntc			<u> </u>		Ľ	_ <u>v</u>			<u> </u>					٧	٧	_	_			·	
				VVI	יננפו	I CX	atti	and	1 H2	oigil	mei	ııs.																				_	_
			Vector revision and 2 D																									' 1	¹ J				
			Vector revision and 3-D coordinates (systems)	<b>√</b>	<b>✓</b>												<b>√</b>	1	/														

Term 6	EE 331	Electric & Magnetic Field I	Columb's law and field intensity  Flux density and Gauss's law theory for electrical field  Divergence theory  Conductors, Dielectrics and  Capacitance  Boundry condition  Current density and resistance calculations poisson's and laplace equations	\[   \lambda   \]   \[   \lambda   \]   \[   \lambda   \]   \[   \lambda   \]   \[   \lambda   \]	✓ ✓					\ \ \		✓ ✓					✓ ✓ ✓ ✓	\[   \lambda   \]   \[   \lambda   \]	\ \(  \)														
•		Assesment Method		۱۸/۶	itton	Fv.	am ·	and	۸ς۰	cian	men	ıtc.		!														丄		Ш			4
		Assesment Method	Single phase trans : theory, operation and autotransfo Three phase induction	vvi ✓				√	√ AS:	Sign	men	its.			Ţ				✓		1	<b>√</b>	✓	1				Ţ		П	$\overline{\downarrow}$	1	
	EE 322	Electrical Machines II	machines: theory, operation and modes of operation.																✓														
			Three phase induction motors	✓	✓		✓	✓	✓								✓	✓	✓			✓	✓	✓									
			Application as induction generator.																✓						✓	✓ .	✓	~		✓	✓	✓	
		Assesment Method		Wr	itten	Exa	ams	, As	sig	nme	ents	and	Lab	ora	tory	Wo	ork.											_		_			
			Introduction to controlled systems (open and closed) systems		✓																												
			Mathimatical modeling of physical system	✓	✓		✓	✓	✓			✓					✓	✓	✓			✓		✓									<b>√</b>
	EE 311	Fundamentals of	Block digram reduction	✓	✓		✓	✓	✓								✓	✓	✓	Щ		✓		✓			Ţ	工		Ш	耳		<b>✓</b>
		Control Engineering	First order system	<b>√</b>	<b>√</b>		<b>√</b>	✓	✓			✓			_	4	<b>√</b>	✓	<b>√</b>	$\sqcup$	_[	✓		<b>√</b>	_	4		丰	1	igspace	$\dashv$	_	<u> </u>
			second order system	<b>√</b>	_	_	<b>√</b>	<b>√</b>	<b>√</b>			✓	$\blacksquare$	_	_	4	<b>√</b>	<b>√</b>	<b>✓</b>	$\vdash \vdash$	4	<b>√</b>		<b>√</b>	$\dashv$	+	_	十		$\dashv$	$\dashv$	4	<u>/</u>
			Error and steady state error Routh's criteria	<b>√</b>	<b>√</b>		<b>√</b>	<b>√</b>	<b>√</b>							$\dashv$	<b>√</b>	<b>√</b>	<b>✓</b>	$\vdash \vdash$	$\dashv$	<b>✓</b>	$\dashv$	<b>✓</b>	$\dashv$	+		十		$\dashv$	$\dashv$	-	$\dashv$
			stability study using bode plot	<b>∨</b>			<b>∨</b>	<b>∨</b>	<b>∨</b>								<b>√</b>	<b>∨</b>	<b>▼</b>			<b>,</b> ✓		·									<b>-</b> ✓
		Assesment Method		Wr	itten	Exa	ams	, As	sig	nem	nts	and	Ma	tlab	Sim	nula	tion															-	

			Steady Magnetic Field (Biot-	✓	✓														✓									I			<b>√</b>			
			Magnetic Forces and	✓	<b>✓</b>																										Т			
			Torques	_	Ĺ			,																							┸			
		Electric & Magnetic	Magnetic matrilas and	✓	/																													
	EE 333	Field II	magnetic circuits	_	Ĺ																										ᆚ			
			Time varying magnetic filed																															
			(Farady's law of induction -	✓	✓														✓										<b>✓</b>		✓			ļ
			motional emf)																									_			4			
			Maxwell's equation	✓	✓																									✓	丄			
		Assesment Method				n Ex	am	s ar	d A	ssigr	nem	nts.																			_			
			Transient in RL	<b>√</b>													<b>√</b>	<b>√</b>	<b>√</b>									4	_	_	4		_	_
			Fault Analysis	✓	✓												<b>√</b>	✓	<b>√</b>									_		_	4		_	_
			Selection of Circuit Breaker		✓												<b>√</b>	✓	<b>√</b>									4	_	_	4			
	EE 441	Power System II	Symmetrical components	✓	✓												✓	✓	<b>√</b>									4	_	_	4		_	_
			Unsymmetrical fult	✓	✓												✓	✓	✓									_		_	4		_	_
			Power system stability under	✓	✓												✓	✓	✓															ļ
			faulty condition		_	<u> </u>			Ļ								Ļ														丄			_
		Assesment Method		Wr	itte	n Ex	am	s, A	ssig	nme	ents	and	Ma	tlab	Sin	nula	itior	۱.						_				_		- 1	_	_	_	_
			Three phase: construction,	✓	✓												✓	✓	✓							✓								
			theory and performance.																									4	_	_	+		4	4
			Three phase synchronous	✓	✓												✓	✓	✓															
			machines construction.																								H	-	-		+	-	-	$\dashv$
7	FF 422	Electrical Machines II	Synchronouns generator operation	✓	✓		✓	✓	✓								✓	✓	✓			✓	✓	✓	✓	✓	✓		✓		<b>✓</b>			
ے ا		in the state of th	Three phase synchronization																	/	<b>✓</b>													
l L			problems																		·							_			4			
Term			Synchronouns motor	<b>√</b>	<b>√</b>		<b>✓</b>	<b>√</b>	<b>✓</b>								<b>✓</b>	<b>✓</b>	<b>√</b>															
•			operation																												4			
			Starting of synchronons	_	,																													
			motor.	✓	✓												✓	✓	✓	<b>✓</b>	✓										丄			_
		Assesment Method		Wr	itte	n Ex	am	s, A	ssig	nme	ents	and	Lab	ora	tory	/ W	ork.																	
			AC Voltage control	✓	✓	✓	✓	✓	✓								✓	✓	✓															✓
			DC Choppers	✓	✓	✓	✓	✓	✓				✓	✓	✓	✓	✓	✓	✓															
	EE 423	Power Electronics II	Cyclo Converter &																									T					T	
			Frequency Changer																					L										
			PWM Inverter	<b>√</b>	✓												✓	✓	✓			✓	✓	✓							1			
		<b>Assesment Method</b>		Wr	itte	n Ex	am	s, A	ssig	nme	ents,	Lab	ora	tory	/ Wo	ork	and	Mir	ni-Pr	ojec	t.													

		Root locus analysis	✓	✓										✓	✓	✓			✓				Т			
		Lead compansator design	✓	<b>✓</b>				✓	✓	✓				✓	✓	✓			<b>√</b>							
		using R.C method				-														<u> </u>			+			
		Lag compansator design using R.C method	✓	✓				✓	✓	✓				✓	✓	✓			✓							
		Lead compansator design	_	_		1				_		-							+		1	1	十	+		
		using Bode Plot method	✓	✓				✓	✓	✓				✓	✓	✓			<b>\</b>							
EE411	Control System I	lag compansator design																								
CC411		using bode plot (frequency	✓	✓				✓	✓	✓				✓	✓	✓			✓							
		response)																					ᆚ			
		Polar plot analysis	✓	✓		_													✓				_			
		Nyguist stability	<b>√</b>	✓		_						_						_	✓	ļ		_	4	_		
		PI controller design	<b>√</b>	✓		_		<b>√</b>	<b>√</b>	<b>√</b>				<b>√</b>	✓	<b>√</b>		_		<u> </u>			4			
		PD controller design	<b>√</b>	<b>√</b>		_		<b>√</b>	<b>√</b>	✓				<b>√</b>	✓	<b>√</b>		_		<u> </u>			4			
		PID controller design	✓			Щ.	Ļ	✓	✓	✓	Ц,		<u>Щ</u>	<b>√</b>	✓	✓							丄			
	Assesment Method	I A I St	Wr	itte	า Exar	ns, A	ssigi	nme	ents	and	Mati	ab Si	imula	ation								_	_		_	
		Architecture of microprocessor and		/																						1
		microcontrollers																								·
		Memory Organization and																					T			
		microcontroller																							,	
		programming																						*		
															,	-										
										✓				✓	✓	✓										
		Input/output ports with								✓				<b>√</b>	<b>√</b>	<b>√</b>										
		Input/output ports with applications								<ul><li>✓</li></ul>				<b>√</b>	<b>✓</b>	<b>√</b>										
		applications								✓																
										✓ ✓					<b>✓</b>											
		applications  Timer modules and counters								✓ ✓				<b>√</b>	<b>✓</b>	✓										
		applications  Timer modules and counters  Interrupts: Software and								✓				<b>√</b>										✓		
	Microprocessor	applications  Timer modules and counters								✓ ✓				<b>√</b>	<b>✓</b>	✓								<b>√</b>		
EE 413	Based Process	applications  Timer modules and counters  Interrupts: Software and								✓ ✓				✓	✓	✓							+	<b>✓</b>		
EE 413	•	applications  Timer modules and counters  Interrupts: Software and								✓ ✓	× ,		· •	✓	✓	✓							\\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\	<b>✓</b>		

			Operational amplifiers and signal conditioning circuits			✓																			
			Analog to Digital converter and Data acquisition with								✓					<b>✓</b>	<b>✓</b>	<b>√</b>			Ì				<b>✓</b>
			Serial port interface with applications								<b>✓</b>					<b>&gt;</b>		<b>✓</b>							✓
		Assesment Method		Wr	itte	n Exa	ams,	Assi	gnm	ents	and	Mi	ni-Pı	roje	ect.					 		1	1 1	 _	
			State Model of Linear Systems using Physical Variables	✓	✓																				
			State Space Representation using Physical Variables	<b>✓</b>	<b>✓</b>											<b>✓</b>	<b>✓</b>	✓							✓
∞			State Space Representation using Canonical Variables	✓	✓											✓	✓	✓							✓
Term 8		Control System II	Properties of Transition Matrix	<b>✓</b>																					
	EE 412		Solution of State Equations	<b>✓</b>	~																				<b>✓</b>
			Introduction to Pole Placement in State	✓	✓				~	<b>√</b>	✓					✓	<b>√</b>	✓							<b>✓</b>
			Introduction to Nonlinear Control Systems	✓	✓																				✓

		Describing Function and the Phase Plane Methods	✓	<b>√</b>										✓	<b>√</b>	✓													
	Assesment Method		Wr	itten	Exan	ns, A	ssigr	ımer	nts an	ıd ſ	Matla	b Si	mula	ation	۱.														
		General Principles of						✓		I							✓	✓							✓	I		✓	Т
		Operation of the different types of relays							~	\				✓										<b>~</b>					~
EE 442	Powe System Protection I	Circuit breakers and fuses						✓																		I			
	Frotection	Protection of the various components of power system														<b>√</b>							✓						
	Assesment Method		Wr	itten	Exan	ns, A	ssigr	mer	nts an	ıd E	Etap S	imu	ulatio	n.		<u> </u>										+		_	Ľ
		Single Phase DC motor Drives	✓							Ī	İ			✓	✓	✓										Ī		T	Γ
		Semi and Full converter DC drives	✓	<b>✓</b>										✓	✓	✓													
		Dual Converter	✓	<b>√</b>						T				✓	✓	✓								1	T	T		T	T
		Reversible drives	✓	✓						Ī				✓	✓	✓				1						T			
		Three-Phase Drives	✓	✓										<b>✓</b>	✓	✓													
EE424	Electrical Drives I	Closed Loop Control of DC Drives																	✓	✓	<b>√</b>								
		DC Choper drives for DC Motors	✓	✓										✓	✓	✓													
		Induction Motor Drives,Operation & Performance	<b>✓</b>	<b>✓</b>										✓	<b>✓</b>	✓													
		Voltage & Freq. Control	<b>✓</b>	<b>√</b>	+	-		+	-	╁	-			✓	✓	✓					$\dashv$	+	+	+		十	-	╁	+
		Stepper Motor		<b>√</b>	$\top$					t		T							✓		✓		+	1	1	/ ,	<b>√</b> ✓	+	t
	Assesment Method		Wr	itten	Exan	ıs, A	ssigr	mer	nts an	d F	Resea	rch																	t
		Classification and history of renewable energy re¬sources.							<b>√</b>													✓	<b>✓</b>	<b>√</b>					
		Wind energy basics		$\vdash$	+		H		-	╁	+	H	$\vdash$						$\dashv$	+	$\dashv$	$\dashv$	+	+	-	+	+	+	<b>+</b>
		Fixed speed wind turbines						<b>√</b>	<b>✓</b>	t																+		T	
					+			_	_	╅	-1-	╁	$\vdash$	Н					+		$-\mathbf{f}$	f		$\dashv$	-	十	+	1	t

			Variable speed wind turbines												Ī											
			Vector control of Power electronics converters for wind generators							٧																✓
[S]			Solar energy basics																							✓ 
ırse		Fundamentals of	Photovoltaic and fuel cells						✓																✓	
[Elective Courses]	EE 523	Renewable Energy	Power electronics in solar systems						✓																	<b>✓</b>
tive			Hydropower						✓																✓	
ilec			Biomass						✓																✓	
=			Grid integration for electricity generated from							٧																
			Effect of government regulation (grid code) on the renewable energies industry															<b>✓</b>								
			State of the industry																							<b>✓</b>
		Assesment Method		Writ	ten	Exan	ns, Q	uizze	es																	
		Electrical Power	Conventional P.S: Thermal and Internal Combustion Hydrulic		√ √				<b>√</b> .	√					✓	<ul><li>✓</li></ul>								<b>/</b>		
	EE 542	Station	Nucler Renewable Energy P.S: wind, photovoltaic and solar thermal		✓ ✓				<b>√</b> .	✓ <b>∨</b>	<u> </u>		✓		✓	✓		<b>✓</b>	· •	<b>√</b>	<b>✓</b>	✓	✓ ,	<b>/</b>		

		Assesment Method		Wr	itten	Exa	ms																							
			Voltage Profile & Regulation						✓							✓														
[5:	EE 543	Electrical Power Distribution	Distributed Substation Design, Load Distribution & Service Area of Distributed Substation						<b>✓</b>	<b>✓</b>	<b>~</b>																			
ırse		Distribution	Operation of Distributed Substation						✓	✓																				
[Elective Courses]			Low Voltage Distribution in Residential and Commercial Areas						<b>√</b>	✓	<b>√</b>					<b>✓</b>	✓	✓												✓
ti		Assesment Method		Wr	itten	Exa	ms, N	∕lini-	Proj	ect.								· ·												
[Elec			Control problems in electrical power system  Modeling system							✓																				
	EE 542	Control Application in Power	components in power system dynamics						✓							✓	✓	✓												
		Engineering	Excitation control systems  QV control						✓	✓	✓																			
			Generation control systems PF control							✓																				✓
		Assesment Method			itten	Exa	ms																							
			Sampling Theory study	✓	✓	_	-		✓							✓	✓	✓		4	_	_	4	_		4	4	-	_	
			Z-Transformation and Discreet state space analysis	✓	✓				✓		✓					✓	✓	✓												✓
	EE 515	Computer Control	Discreet state space studies Drscretization	✓	✓											✓	✓	✓												✓
	LL 313	of Dynamic Systems	Deadbeat response and pole placement design	✓	✓				✓							✓	✓	✓												✓
			Application of computer control of dynamic system (such as PLC,SCADA, DCS)		<b>√</b>							<b>✓</b>	<b>✓</b>	<b>✓</b>	✓				<b>✓</b>		✓	<b>✓</b>	✓	<b>✓</b>	<b>✓</b>		~	<b>/</b>		✓
		Assesment Method		Wr	itten	Exa	ms,A	ssign	me	nts																				

EE 541	Power Systems Protection II	Review of static/digital versus electomechanical relays Components detectors and applications, hardware of digital relays Mathematical background for digital protection Digital relays for motor, transmission line and machine protection Integration of protection and control in substations					✓ ✓ ✓	✓				✓	√ V	✓								✓ ✓
		Traveling wave based protection										~	,									
	Assesment Method		Writt	en Ex	ams															 		_
		Terms used in illumination and laws of illumination  Design of illumination schemes		$\frac{1}{1}$			✓					<b>✓</b>	· •	<b>√</b>								<b>✓</b>
EE 547	Utilization of Electrical Energy	Electric heating, arc furnaces and electric welding					<b>√</b>															
	Liectrical Lifergy	Traction system characteristics and control					✓															
		Electrolytic processes. Refrigeration and air conditioning					✓															
		Electric safety engineering					✓	✓														
	Assesment Method		Writt	en Ex	ams	, Min	i-Pro	ject.														
		Characteristics of industrial & commercial loads										<b>~</b>	,									
		Selection of distribution system and wiring systems						✓	✓													~
	Design of Electrical and	System protection and coordination					✓		✓				<b>✓</b>	✓								~
	Electromechanical	Controllers and MCC	H	1	H		1		✓	1	1	1	<b>√</b>	✓	l		1	T			1	T
EE 548	Systems for	Power factor correction		1	H			✓		T							1	T				T

		Industrial Installations	Lighting, HVAC, Lifts and escalators							~			<b>√</b>					✓	✓	✓										<b>~</b>
		ilistaliations	Grounding, Special Loads							~	<b>7</b>	<b>√</b>	✓														T	T	1	✓
			Safety and Fire Alarm Safety									<b>√</b>																		
			Codes and Standards							<b>v</b>	/							✓												
		Assesment Method		Wr	itte	n E	xam	ıs,N	1ini	-Prc	jeo	cts a	ınd	Eta	p Si	mu	latio	on.												
			Automated hierarchical levels and components																							<b>√</b>		,	/	
es			Introduction to PLC.S.																							✓		,		
[Elective Courses]	FF F43	Automated	Hardware configuration and descriptions				<b>√</b>																			<b>√</b>		,	/	
tive	EE 512	Industrial Systems (1)	Programming and testing basic functions	✓	✓	✓														✓			~							✓
[Elec			Programming and testing advanced functions	✓	✓	✓														<b>✓</b>			<b>✓</b>							<b>✓</b>
			Industrial Applications using PLCs	✓	✓	<b>✓</b>	<b>✓</b>	· /										<b>✓</b>	<b>✓</b>	<b>✓</b>			~					,	/	✓
		Assesment Method		Wr	itte	n E	xam	ıs,N	1ini-	-Prc	jed	cts.																		
			Generation and measurement of high voltage AC and DC	✓	✓	✓		<b>✓</b>		\ \ \																				
		High Voltage	Sources of transients in power system	✓	<b>√</b>													✓	<b>✓</b>	✓										
	EE 545	Engineering	Travelling waves	✓	✓													✓	✓	✓							$\prod$	$\prod$		
			Insulations, lattice diagram and surge arresters	✓	✓													✓	✓	✓										
			High voltage switchgears																											<b>✓</b>
		Assesment Method		Wr	itte	n E	xam	ıs,A	ssig	nm	en	ts.		-							-		•							

	EE554	Power System 3	Cost of Generation	√		<b>V V V</b>		٧		
			Dispatch	٧		<b>V V</b>		٧		
			Power SystemHarmonics	٧	٧	<b>V V</b>				
			Reliability	٧		<b>V V</b>				
			Load Forecasting	٧		٧ <i>٧</i> ٧				П